

An Investigation of the Dependence of 3D Semi-Span Wing Behaviour on the Leading-edge Tubercles Configuration

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Abstract:

Inspired by nature, experiments on the aerodynamic behavior of wings and wind turbines with sinusoidal leading-edge continued over the last two decades. The studies showed promising results at post-stall flow regimes as tubercles cause a more gradual lift loss and a higher stall angle of attack. This study aims to investigate numerically the dependence of the wing's aerodynamic coefficients on the tubercle's wavelength and amplitude at the stall angle of attack and 3D flow regime. The results show that increasing the tubercle's average amplitude up to 0.02 of the average chord increases the lift coefficient by 23.61% and decreases the drag coefficient by 4.61%. Similarly, decreasing the wavelength especially up to 1.1096 of the average chord increases the lift coefficient up to 21.55% and decreases the drag coefficient by 9.50%. Flow visualization shows that zones of attaching and separation flow form on the suction surface of the scalloped wings whereas the baseline wing is in a deep stall.

Keywords: Leading-edge tubercles; Computational fluid dynamics; Aerodynamics; Parametric study.

Abbreviation:

2D	two dimensional	$C_{L, \max}$	maximum lift coefficient
3D	three dimensional	P1	amplitude design parameter

Amp	amplitude	C_L/C_D	lift to drag ratio
AoA	angle of attack [deg]	P2	wavelength design parameters
C_{avg}	Average chord	Re	Reynolds number [-]
C_L	lift coefficient	V	velocity [m/s]
C_D	drag coefficient	y^+	non-dimensional distance

Greek letter

λ Wavelength

1 **1. Introduction**

2 Over the last two decades, the aerodynamic behavior of wings and wind turbines
3 with leading-edge tubercles was tested experimentally and numerically. Watts and
4 fish [1] studied numerically a scalloped wing at the angle of attack (AoA) 10°
5 using the panel method and in 3D numerical code. Watts and Fish [1] found that
6 the lift coefficient increased by 4.8%, and the lift to drag coefficient increased by
7 17.6% in the case of the scalloped wing. Watts and Fish [1] suggested that using
8 tubercles would be more beneficial in AoAs larger than 15° .

9 Miklosovic et al. [2] experimentally evaluated the aerodynamic coefficients for
10 finite and infinite wings with and without tubercles. Miklosovic et al. [2] found
11 that scalloped wings had a gentler stall behavior in both finite and infinite wings.
12 Tubercles were more beneficial for the 3D wing. In contrast to the scalloped
13 airfoil (2D), the scalloped 3D wing had a higher maximum lift coefficient and
14 larger stall angle than the baseline wing. Miklosovic et al. [2], and Hansen et. al.
15 [3] suggested that this flow behavior may be due to the change in local AoA.
16 Although the change in local AoA creates a vortex-dominated flow, the results
17 were not similar to wings with the traditional vortex generators [4]. Van Nierop
18 et al. [5] stated that in contrast to tubercles the vortex generators' amplitude [4] is
19 in order of magnitude of the boundary layer thickness.

1 Hansen et al. [3] studied the effect of tubercle's amplitude, wavelength, and
2 amplitude to wavelength ratio on airfoils. Although wings with large amplitudes
3 had a more gradual lift loss in the post-stall flow regime, wings with smaller
4 amplitudes had a higher maximum lift coefficient. The baseline wing had the
5 highest maximum lift coefficient. Reducing the wavelength for a certain point
6 increased the maximum lift coefficient, and stall angle, and had a gentler lift loss.

7 Nierop et al. [5] constructed a mathematical model to predict the influence of the
8 tubercles on the wing's aerodynamic characteristics. Nierop et al. [5] found that
9 as the tubercles amplitude increases the lift losses increase before the critical angle
10 of attack. After the critical angle of attack, the stall became more gradual. The lift
11 coefficient was insensitive to wavelength change.

12 Bolzon et al. [6] studied the effect of tubercles on swept wings at pre-stall flow
13 regimes. Bolzon et al. [6] found that tubercles increase lift to drag coefficient
14 (C_L/C_D) by reducing drag coefficient at angles of attack (AoAs) smaller than 8° .
15 for AoAs higher than 8° , all aerodynamic coefficients were reduced as flow
16 separates behind tubercles valleys.

17 Post et. al. [7] evaluated experimentally the aerodynamic coefficients of the
18 baseline wing and five different scalloped wings. All scalloped wings had a
19 gradual lift loss after stall. The scalloped wings with tubercles configuration
20 similar to Hansen et al. [3] optimal design achieved the highest stall angle and
21 best post-stall flow behavior. Straight wings achieved higher lift than swept
22 wings. Post et al. [7] argued that by normalizing the area, the lift coefficient of the
23 swept wings was higher than the straight wings. More research is needed on swept
24 scalloped wings behavior.

25 Ibrahim et al. [8] compared a baseline wind turbine with slotted and scalloped
26 wind turbines. The slotted wind turbine outperformed the baseline wind turbine
27 at low wind speeds ($v \leq 6.5$ m/s). On the other hand, the scalloped wind turbine

1 had a better performance at high wind speed ($v > 6.5$ m/s) and under harsh weather
2 conditions.

3 Abate et al. [9] tested the performance of wind turbines with different tubercles
4 configurations and their effect on power and annual energy production. Abate et
5 al. [9] found a considerable improvement for all tubercles configurations in high
6 wind speeds and stall conditions. At low speed, tubercles degraded the wind
7 turbine performance. Abate et al. [9] stated that tubercles generate counter-
8 rotating vortices that prevent spanwise flow.

9 Ke et al. [10] investigated the influence of wind velocity on a sinusoidal leading-
10 edge wind turbine. Ke et al. [10] found that tubercles were beneficial at off
11 conditions and high wind velocity ($V \geq 7$ m/s), while tubercles degraded generated
12 power at the on conditions and low wind speed ($V < 7$ m/s).

13 Lohry et al. [11] conducted a multi-objective optimization algorithm for the
14 maximum lift coefficient (C_L) at angles of attack 14° , and 20° in an airfoil case.
15 Lohry et al. [11] found that there is no single geometry that has optimum lift
16 coefficient at both pre-stall and post-stall flow regimes. Lohry et al. [11]
17 suggested that the tubercles serve as vortex generators. The improvement in the
18 wing behavior is due to the interaction between the wing's tip vortex and leading-
19 edge vortices.

20 Paula et al. [12] studied the effect of Reynold number (Re) on the baseline wing
21 and on three scalloped wings with different leading-edge configurations (wings
22 with tubercles at different amplitudes and wavelengths). Re ranged from 0.5×10^5
23 to 2.9×10^5 . Paula et al. [12] found that the smallest amplitude and wavelength
24 achieved the best performance between the four wings. The scalloped wing with
25 the smallest amplitude and wavelength outperformed the baseline maximum lift
26 coefficient by 19.4% and delayed the stall angle from AoA 10° to 20° at Re equals
27 1.2×10^5 .

1 Lu et al. [13] optimized leading-edge tubercles geometry. The objective functions
 2 were delaying stall and increasing lift coefficient between AoAs 12° and 16° .
 3 Based on the Pareto front [14], four geometries were selected that achieve the two
 4 optimization objectives. Although the increase in lift coefficient between angles
 5 12° , and 16° , the lift coefficient was smaller than the baseline wing for other angles
 6 of attack.

7 Cai et al. [15] studied the flow pattern around an airfoil at both the pre-stall and
 8 post-stall flow regimes. Cai et al. [15] found a periodic flow regime of flow
 9 separation behind valleys and attached flow behind peaks at small AoAs. After
 10 the stall angle of attack, an aperiodic and asymmetric flow pattern formed around
 11 the wings, as the flow separates only behind some valleys. The distance between
 12 the stalled valleys was stated to be 4-7 times the tubercles' wavelengths.

13 Custodio et al. [16] examined seven different wings with sinusoidal leading-edge
 14 protuberances in a water tunnel. Re ranged between 0.9×10^5 and 4.5×10^5 .
 15 Custodio et al. [16] found Re number effect negligible beyond 3.6×10^5 . Although
 16 the scalloped wings had a maximum lift coefficient equal to, or greater than the
 17 baseline wing, all scalloped wings had drag coefficients higher than the baseline
 18 wing.

19 Kim et al. [17] studied the influence of tubercles on wing behavior at Re equals
 20 1.8×10^5 . Tubercles delayed stall from AoA 8° to 15° and increased the maximum
 21 lift coefficient by 22%. Separation starts at the wings' tip for both the baseline
 22 and scalloped wings, but in the case of the scalloped wing, counter-rotating
 23 streamwise vortices served as a fence to prevent separation progression in a
 24 spanwise direction.

25 Wei et al. [18] investigated the performance of baseline and scalloped wings in a
 26 3D flow regime. A scalloped wing achieved the highest stall angle, $C_{L, \max}$, and
 27 $\max C_L/C_D$ coefficient. It has also a more gradual lift loss than the baseline wing.
 28 Wei et al. [18] stated that the scalloped wing's performance depends on the

1 tubercle's orientation relative to the flow direction. The scalloped wing had a
 2 higher C_D and lower lift/drag ratio than the baseline for almost all angles of
 3 attacks. Table 1 shows a brief description of the selected literature on the
 4 performance of the scalloped wings.

5 This study aims to investigate the impact of tubercles' amplitude and wavelength
 6 on the scalloped wing's lift, drag and lift to drag coefficients. The angle of attack
 7 16° was chosen for the analysis at the 3-D flow regime. The influence of
 8 sinusoidal leading-edge on the flow pattern around the wing would be also
 9 studied.

10 Table 1 Selected previous investigation of the aerodynamic performance of the
 11 scalloped wings and wind turbines.

Ref.	Exp. / Num.	Wing's Airfoil	2D / 3D	Re (X 10^5)	AoA (deg)	Observations
Watt & Fish [1]	Num.	NACA 63 ₄ -021	2D	---	10°	Scalloped wing had a 4.8% increase in lift, a 10.9% reduction in induced drag, and a 17.6% increase in the lift to drag ratio.
Miklosovic et al. [2]	Exp.	NACA 0020	2D 3D	2.74 5.34–6.31	0° – 22°	<ul style="list-style-type: none"> • Higher $C_{L, \max}$ at the critical angle of attack. • a more gradual lift loss in the post-stall flow regime.
Hansen et al. [3]	Exp.	NACA 0021 & NACA 65-021	2D	1.2	0° – 25°	<ul style="list-style-type: none"> • Lower $C_{L, \max}$ than the baseline wing. • a more gradual lift loss in the post-stall flow field. • The optimum configuration has a small amplitude and small wavelengths.

1 Table 1 Selected previous investigation of the aerodynamic performance of the
 2 scalloped wings and wind turbines (continued).

Ref.	Exp. / Num.	Wing's Airfoil	2D / 3D	Re (X 10 ⁵)	AoA (deg)	Observations
Bolzon [6]	Exp.	NACA 0021	3D	2.25	0°-20°	<ul style="list-style-type: none"> • For swept wings, tubercles reduced C_D and increased C_L/C_D for AoAs less than 8°. • For larger AoAs, C_L and C_L/C_D are smaller than the baseline wing.
Post et al. [7]	Exp.	NACA 0020	3D	1.0 – 5.0	0°-24°	<ul style="list-style-type: none"> • The influence of the Reynolds number was negligible in the case of scalloped wings. • The stall was more gradual in the case of the scalloped wings.
Ibrahim et al. [8]	Exp.	NACA 4412	3D	----	----	<ul style="list-style-type: none"> • Tubercles delayed stall in the case of wind turbines and had a steadier response to wind speed change.
Abate et al. [9]	Num.	S809 (NREL VI wind turbine)	3D	U = 5, 10, 15, 20, 25 m/s	----	<ul style="list-style-type: none"> • The turbine's performance increases for small amplitude, large wavelength, and when only 5% or 38 % of the blade is covered with tubercles.

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 6

1 Table 1 Selected previous investigation of the aerodynamic performance of the
 2 scalloped wings and wind turbines (continued).

Ref.	Exp. / Num.	Wing's Airfoil	2D / 3D	Re (X 10 ⁵)	AoA (deg)	Observations
Ke et al. [10]	Num.	S809 (NREL VI wind turbine)	3D	----	----	<ul style="list-style-type: none"> • For $U \leq 7$ m/s, power generation degraded for scalloped wind turbines. • For $U > 7$ m/s, power generation increased for scalloped wind turbines.
Lohry et al. [11]	Num.	NACA 0020	2D	5.0	14° & 20°	<ul style="list-style-type: none"> • At $AoA = 14^\circ$, the baseline wing was the optimum configuration, whereas the large wavelength scalloped wings were the optimum configuration at $AoA = 20^\circ$.
Paula et al. [12]	Exp.	NACA 0030	2D	0.5 - 2.9	0°- 30°	<ul style="list-style-type: none"> • Small amplitude and small wavelength scalloped wing had $C_{L, max}$.
Cai et al. [15]	Exp.	NACA 634-021	2D	1.8	-15° – 30°	<ul style="list-style-type: none"> • Scalloped wings had a more gentle and stable stall behavior.
Custodio et al. [16]	Exp.	NACA 634-021	2D	0.9 – 4.5	0°- 30°	<ul style="list-style-type: none"> • For scalloped wings, the Re effect was negligible for Re higher than 3.6×10^5. • Scalloped wings had C_D higher than the baseline wing so lower C_L/C_D.
Kim et al. [17]	Exp.	NACA 0020	3D	1.8	0° – 25°	<ul style="list-style-type: none"> • Tubercles delayed stall from $AoA 8^\circ$ to 14°. • Tubercles increased $C_{L, max}$ by 22%.
Wei et al. [18]	Exp.	SD7032	3D	2.2	-7° – 29°	<ul style="list-style-type: none"> • The scalloped wing has a higher stall angle of attack, $C_{L, max}$, and a more gradual stall behavior.

3

1 2. Methodology

2 2.1 Numerical Setup

3 The wings model is based on the geometry studied in both Ref. [2], and Ref. [7].
 4 The wing geometry is based on the humpback whale flipper. The wing profile is
 5 NACA 0020 airfoil, and the equations for the original leading and trailing edges'
 6 profiles are

$$x_{LE} = 2.916 + 0.0624y + 0.000428y^2 - 0.000462y^3, \quad (1)$$

7 and

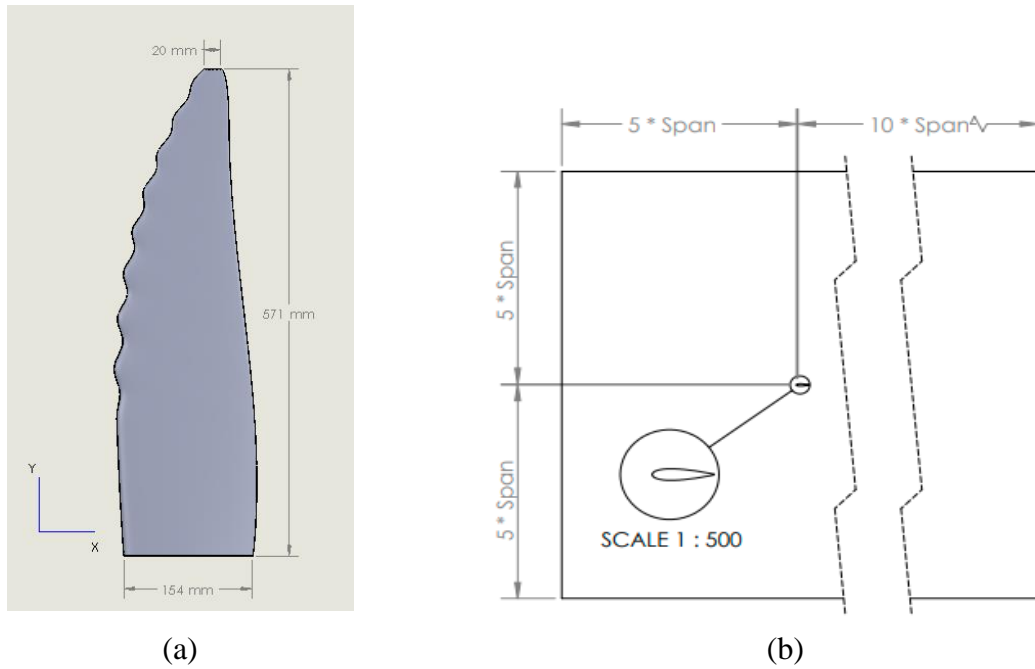
$$x_{TE} = \begin{cases} -3.152 - 0.113y + 0.0194y^2 - 0.000552y^3, & y \leq 507 \text{ mm} \\ -0.374\sqrt{1 - 0.158(y - 19.98)^2} - 1.7, & 507 \text{ mm} < y \leq 571 \text{ mm}. \end{cases} \quad (2)$$

8 The sinusoidal leading edge of the wing is presented as,

$$\Delta x_{LE} = 0.125(1 - 0.001y^2) \sin(0.57y^{1.5} - 0.4) (\tanh(y - 7) + 1). \quad (3)$$

9 The computational domain extends in every direction by five times the span
 10 except for the distance to the outlet which extends ten times the span. The mesh
 11 was generated using ANSYS Mesh. Inflation layers were created around the wing
 12 to achieve an average y^+ less than one, so the buffer layer was avoided. An
 13 unstructured mesh of 6 million elements was used. The mesh has a skewness less
 14 than 0.85 and a minimum orthogonal quality higher than 0.01. The wing and the
 15 domain are shown in Figure 1.

16 The computational simulation was performed using ANSYS-Fluent at $Re = 5.7 \times$
 17 10^5 . The transition SST turbulence model [19] was used. The transition SST
 18 turbulence model is a development of the $k-\omega$ SST turbulence model, and it's
 19 more suitable for the transitional flow regime as a part of the boundary layers is
 20 laminar. For the turbulent boundary layer, transition SST is reduced to $k-\omega$ SST.
 21 For the coupling between the pressure and velocity, The SIMPLEC algorithm was
 22 used with the second-order discretization. The boundary conditions were defined
 23 as velocity inlet, pressure outlet, and symmetry for the remaining boundaries.



1 Figure 1 Schematic drawing for the geometry and the domain. (a) The baseline
 2 wing, and (b) the domain.

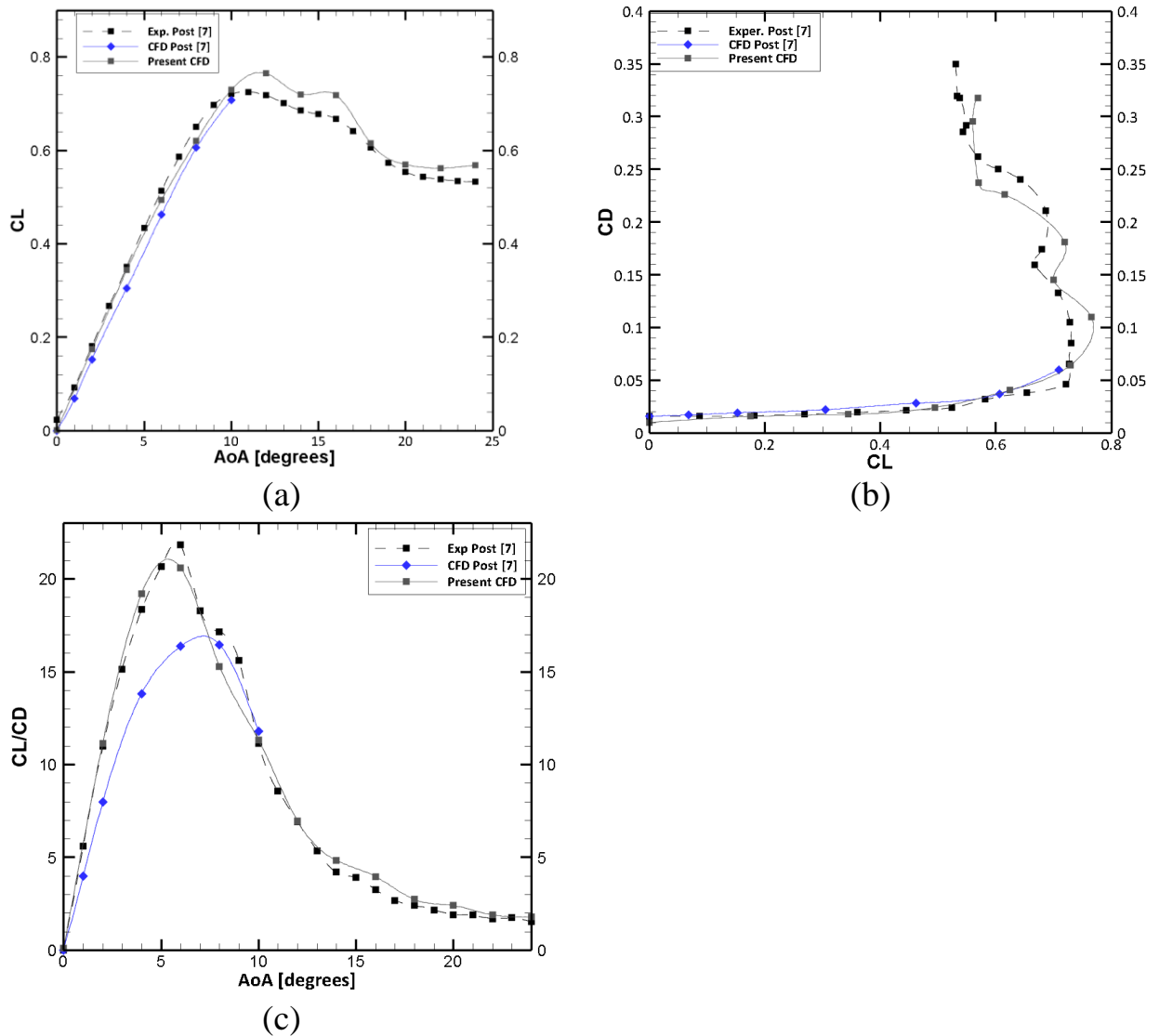
3 The simulation was started as a steady-state simulation for faster conversion and
 4 after two hundred iterations, it was changed to an unsteady state simulation. The
 5 solver iterates in each time step until all residuals converge to less than 10^{-4} or a
 6 maximum number of iterations (50 iterations) is exceeded. The simulation stops
 7 when the fluctuation in the aerodynamic coefficients and y^+ is less than 5% of the
 8 average.

9 Table 2 Mesh independence test.

Case No.	Elements Number	C_L/C_D	Error in C_L/C_D with respect to Ref. [7]
M1	4.6e5	13.3	-22.3%
M2	5.1e5	13.84	-19.2%
M3	5.6e5	14.9	-14.3%
M4	6.5e5	16.27	-5.1%
M5	7.3e5	16.86	-1.6%

1 2.2 Mesh independence test and validation

2 The experimental and numerical results of Ref. [7] were used for the validation
 3 of the numerical model. The grid dependence test was conducted at AoA 8°
 4 similar to Ref. [7]. Five different mesh sizes were used in the mesh independence
 5 test, as shown in Table 2. The M4 mesh was chosen for the validation study as the
 6 error associated with the mesh is small and due to the limited computational cost.
 7 The validation showed a good agreement between the experimental results of Ref.
 8 [7] and the present study results. Table 3 summarizes the properties of the mesh
 9 used in the validation study.



10 Figure 2 Validation of results with the Ref. [7] results for a. C_L coefficient, b. C_D
 11 coefficient, and c. C_L/C_D coefficient.

1

Table 3 Mesh Statistics

	Ansys Mesh Results	Recommended [20]
Y+	0.45	< 1
Max. Y+	3.1	< 5
Minimum Orthogonal Quality	0.02	> 0.01
Maximum Skewness	0.86474	< 0.95
Average Skewness	0.22	< 0.33
Maximum Aspect Ratio	840	< 1000
No. of Elements	5600 000	

2

3 **2.3 Wings Models**

4 Different scalloped wings with NACA 0020 cross-section profiles were evaluated
 5 and compared to the baseline wing. The amplitude and the wavelength were
 6 chosen as the design parameters. The wings configurations with their selected
 7 terminology are presented in Table 4, where \overline{Amp} is the average amplitude, $\bar{\lambda}$ is
 8 the average wavelength, and C_{avg} is the average chord. P1 and P2 are the
 9 corresponding amplitude and wavelength parameters in Eq. 3, respectively. The
 10 wings models were named based on the approximated values of the two design
 11 parameters P1 and P2.

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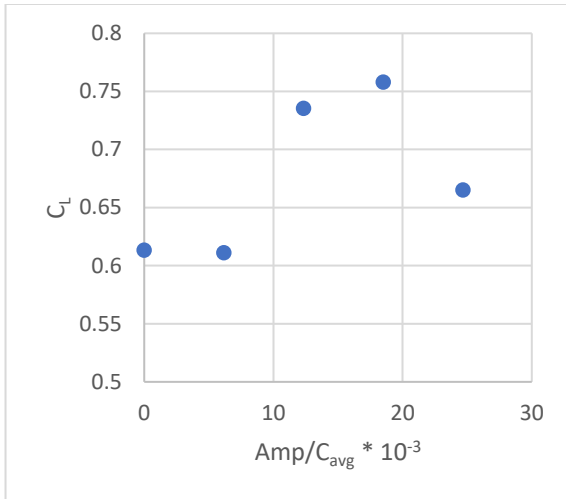
Table 4 Tubercle configurations.

Impact of the amplitude					Impact of the wavelength				
Wing Model	P1	$\frac{\overline{Amp}}{C_{avg}}$	P2	$\frac{\bar{\lambda}}{C_{avg}}$	Wing Model	P1	$\frac{\overline{Amp}}{C_{avg}}$	P2	$\frac{\bar{\lambda}}{C_{avg}}$
A0λ0	0	0	0	0	A0λ0	0	0	0	0
A03λ57	0.03125	0.0067	0.57	0.49	A12λ14	0.125	0.0267	0.1425	2.2192
A06λ57	0.0625	0.0134	0.57	0.49	A12λ28	0.125	0.0267	0.285	1.1096
A09λ57	0.09375	0.02	0.57	0.49	A12λ42	0.125	0.0267	0.4275	0.6340
A12λ57	0.125	0.0267	0.57	0.49	A12λ57	0.125	0.0267	0.57	0.49

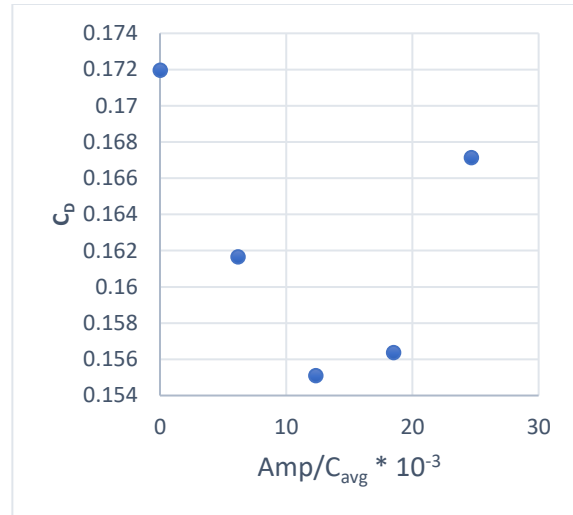
13 **3. Results and Discussion**

14 In this section, the aerodynamic coefficients and flow visualization of the
 15 computational flow around the wings are shown. Figure 3 shows the dependence

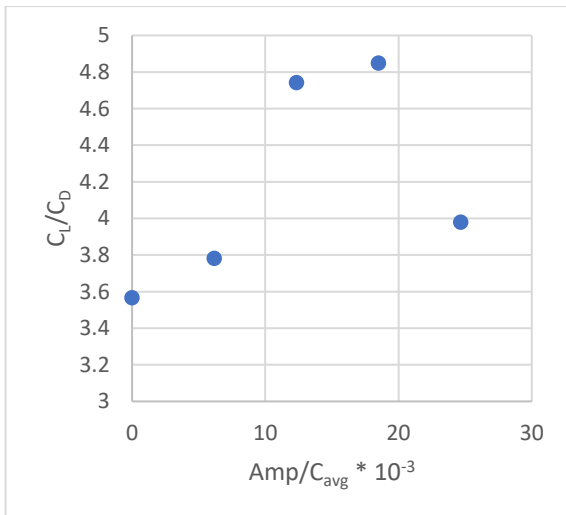
- 1 of the three aerodynamic coefficients C_L , C_D , and C_L/C_D on tubercles' amplitude.
- 2 The wings' performance depends greatly on the tubercle amplitude. For small
- 3 amplitudes, the lift coefficient is approximately constant but with the increase of
- 4 amplitude, C_L increases. The wing model A09 λ 57 achieved the highest lift
- 5 coefficient and lift to drag ratio.



(a)



(b)

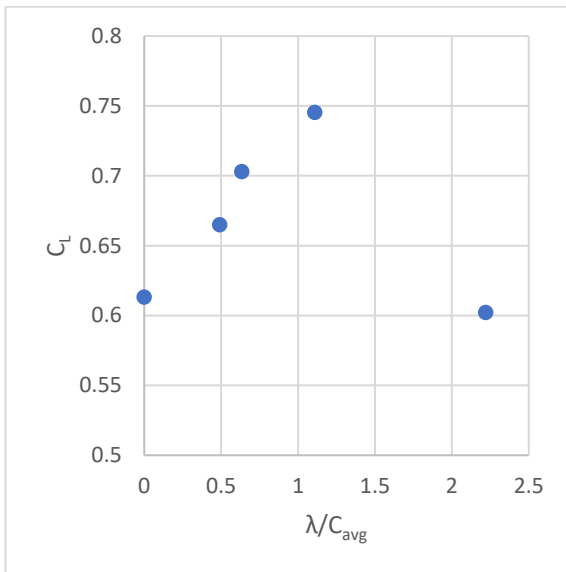


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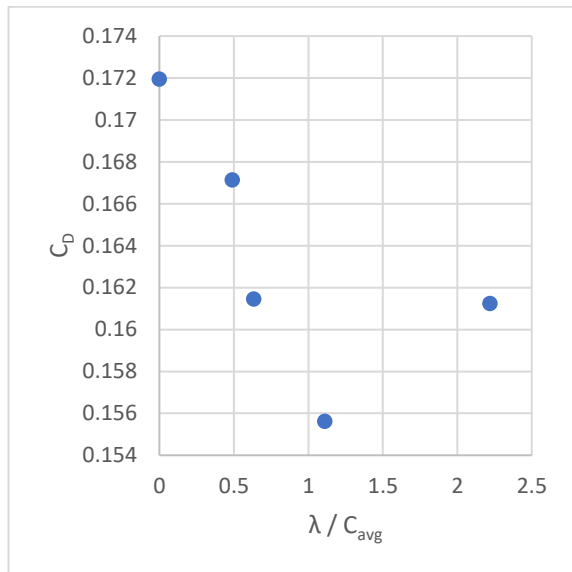
- 6 Figure 3 The dependence of aerodynamic coefficients on tubercle amplitude to
- 7 the average chord at AoA 16° .

- 8 The percentage increase in C_L is 23.1 % by the baseline wing. This result is similar
- 9 to the results obtained by Kim et al. [17]. The conclusion that the scalloped wing

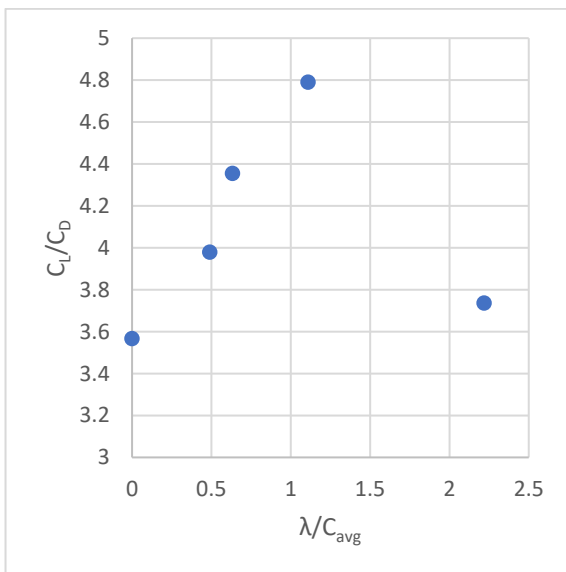
- 1 has $C_{L, \max}$ than the baseline wing was previously approved by Miklosovic et al.
- 2 [2], Kim et al. [17], and Wei et al. [18].



(a)



(b)



(c)

- 3 Figure 4 The dependence of aerodynamic coefficients on tubercle wavelength to
- 4 the average chord at AoA 16° .
- 5 The C_D aerodynamic coefficient decreases with the increase in the amplitude
- 6 parameter. The minimum drag coefficient is achieved by the A06 λ 57 wing. The
- 7 A06 λ 57 wing has a smaller C_D than the baseline wing by 4.61%. The drag

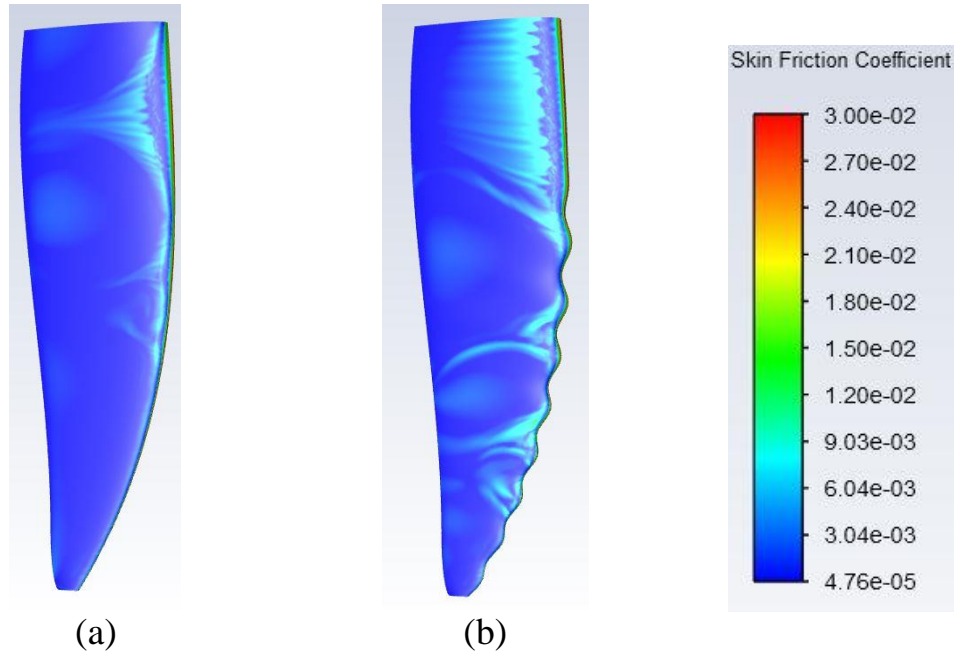
1 increases for larger amplitudes. The baseline wing has the worst aerodynamic
2 performance among all the wings as it has the minimum C_L -except for wing
3 A03 λ 57- and the maximum C_D . As the increasing amplitude increases C_L and
4 decreases C_D , the lift to drag coefficient increases with amplitude.
5 For the smallest amplitude, C_L/C_D is approximately horizontal. Afterward, C_L/C_D
6 increases dramatically with the increase in amplitude. The maximum C_L/C_D is
7 also achieved by the A09 λ 57 wing. The increase in C_L/C_D for the optimum
8 configuration is 35.9%.

9 The wavelength parameter also greatly influences the wing performance, as
10 shown in Figure 4. For large wavelengths and small tubercle fluctuations, there is
11 a small performance degradation as it has a decrease in C_L coefficient by about -
12 1.78%. Decreasing the wavelength, the lift increases largely as the maximum C_L
13 is achieved by the A12 λ 28 wing. The increase in C_L is 21.6% more than the
14 baseline wing. Any decrease in wavelength afterward decreases the lift
15 coefficient.

16 The C_D coefficient decreases with the decrease in wavelength until the minimum
17 C_D coefficient is also achieved by the A12 λ 28 wing. This wing has a drag
18 coefficient less than the baseline wing by 9.5%. While amplitude increases the C_D
19 greatly, the wavelength has a higher influence on the wavelength. Any further
20 decrease in wavelength afterward increases the drag coefficient. Due to the
21 behavior of the C_L and C_D coefficients, the wing with the largest wavelength (wing
22 A12 λ 14) has the smallest C_L/C_D , even smaller than the baseline wing. Any further
23 decrease in the wavelength increases the lift to drag coefficient until the maximum
24 C_L/C_D is achieved by the A12 λ 28 wing. C_L/C_D decreases for smaller wavelengths.

25 Figure 5 shows the skin friction on the upper surface of the baseline and the
26 A09 λ 57 wings. The zones of small skin friction coefficient indicate zones of stall
27 flow. The figure shows that while the flow is completely stalled from the baseline
28 surface, the flow remains attached to the wing A09 λ 57 surface behind the peaks.

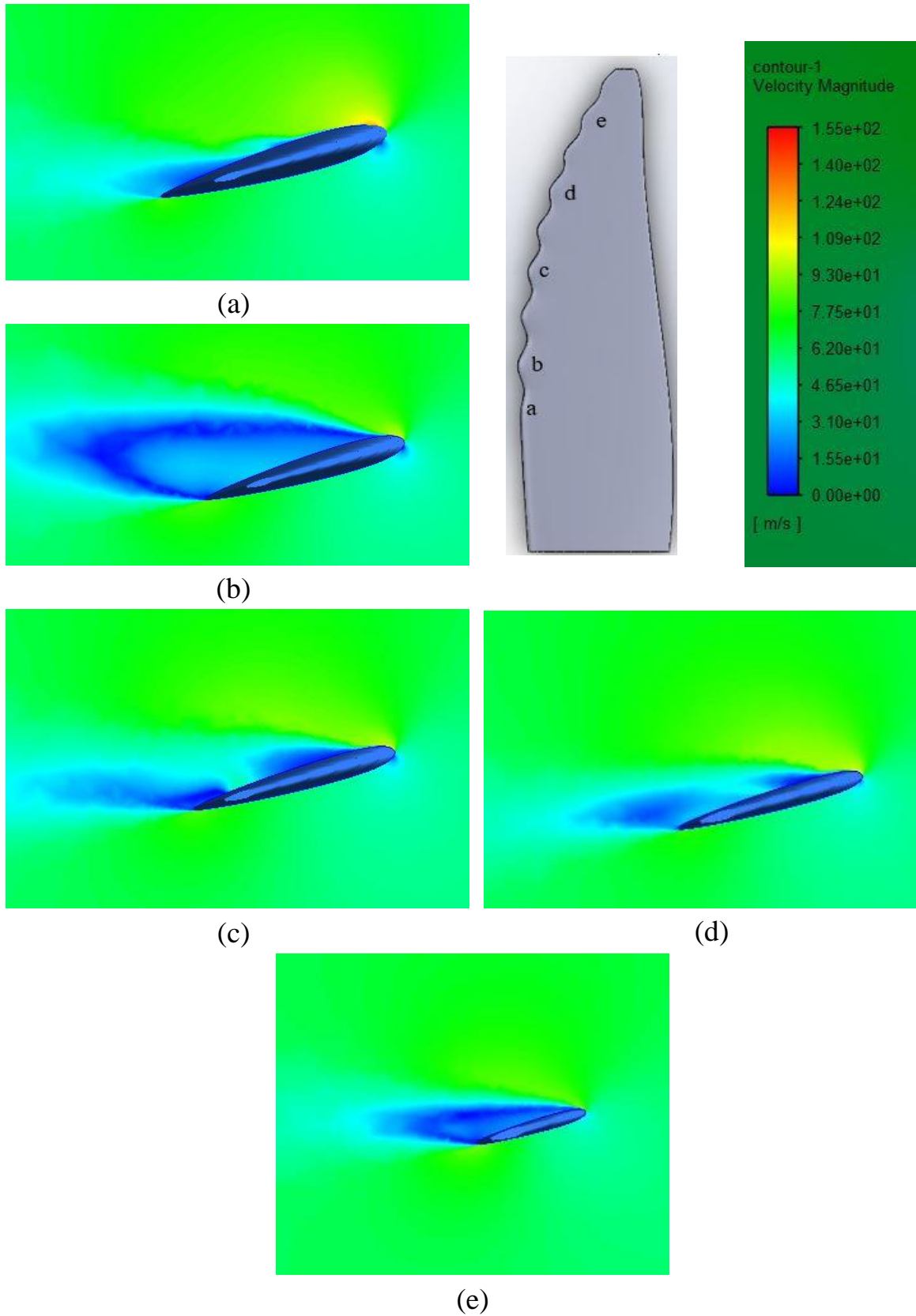
1 Flow separates from the wing's surface behind tubercles valleys. Figure 6, and
 2 Figure 7 show the velocity contours around the A09λ57 wing at cross-sections
 3 located as illustrated on the wing scheme drawn on the upper right side of the
 4 figures.



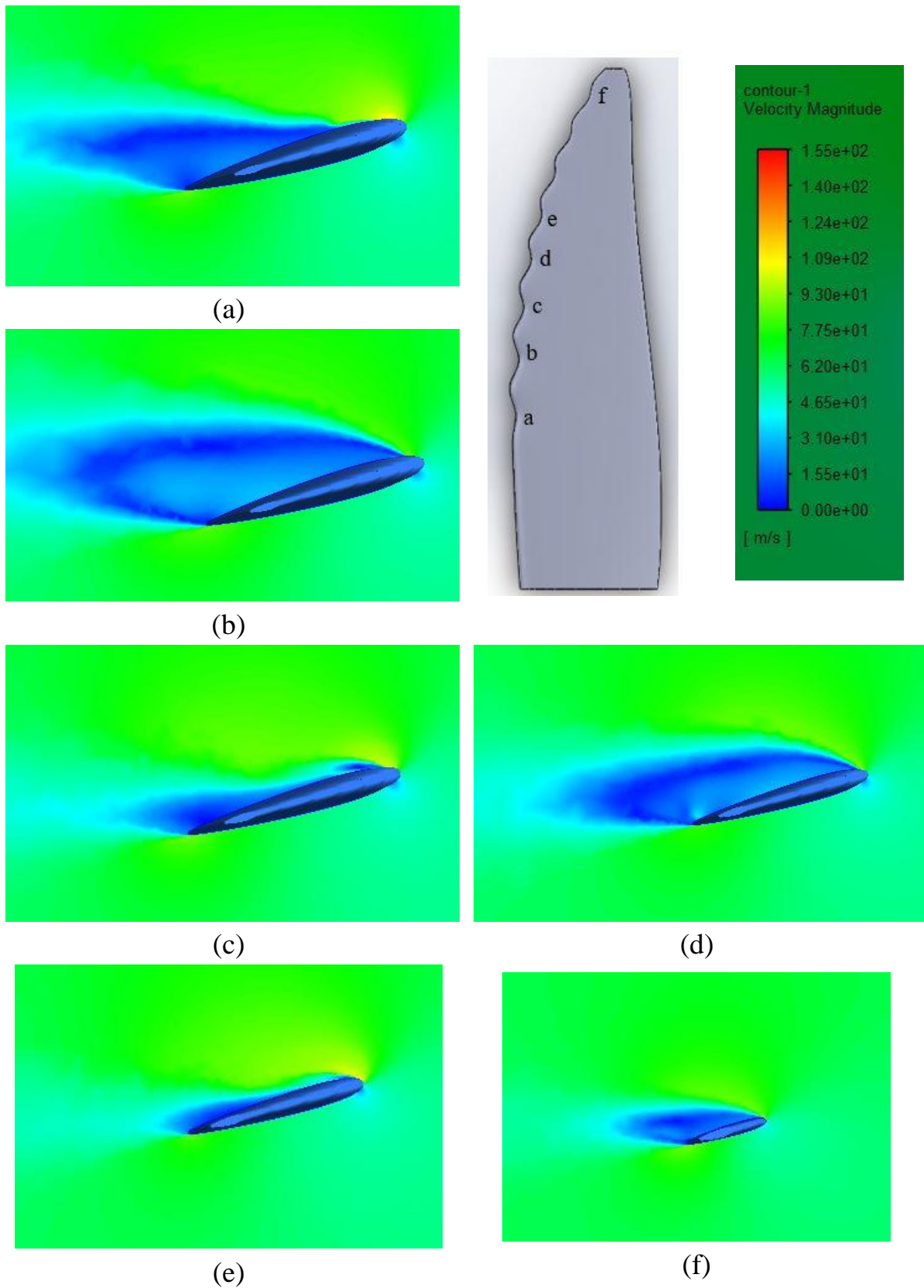
5 Figure 5 Skin friction coefficient at the surface of the suction side of a. baseline
 6 wing, and b. A09λ57 wing at AoA 16°.

7 The flow separates from the wing's surface behind the tubercles valleys while
 8 remaining attached at the tubercles peaks. The flow downstream the valleys is
 9 energized by the attached flow at the tubercles' peaks. This causes the flow to re-
 10 attach to the wing's surface downstream several valleys, especially at the wing's
 11 mid-span. The fluid remains separated behind the other valleys and the separated
 12 flow propagates in a spanwise direction causing the flow to separate downstream
 13 from the neighboring peaks, as shown in Figure 5, Figure 6, and Figure 7. This
 14 flow pattern causes the formulation of attached and separated zones on the wing's
 15 surface.

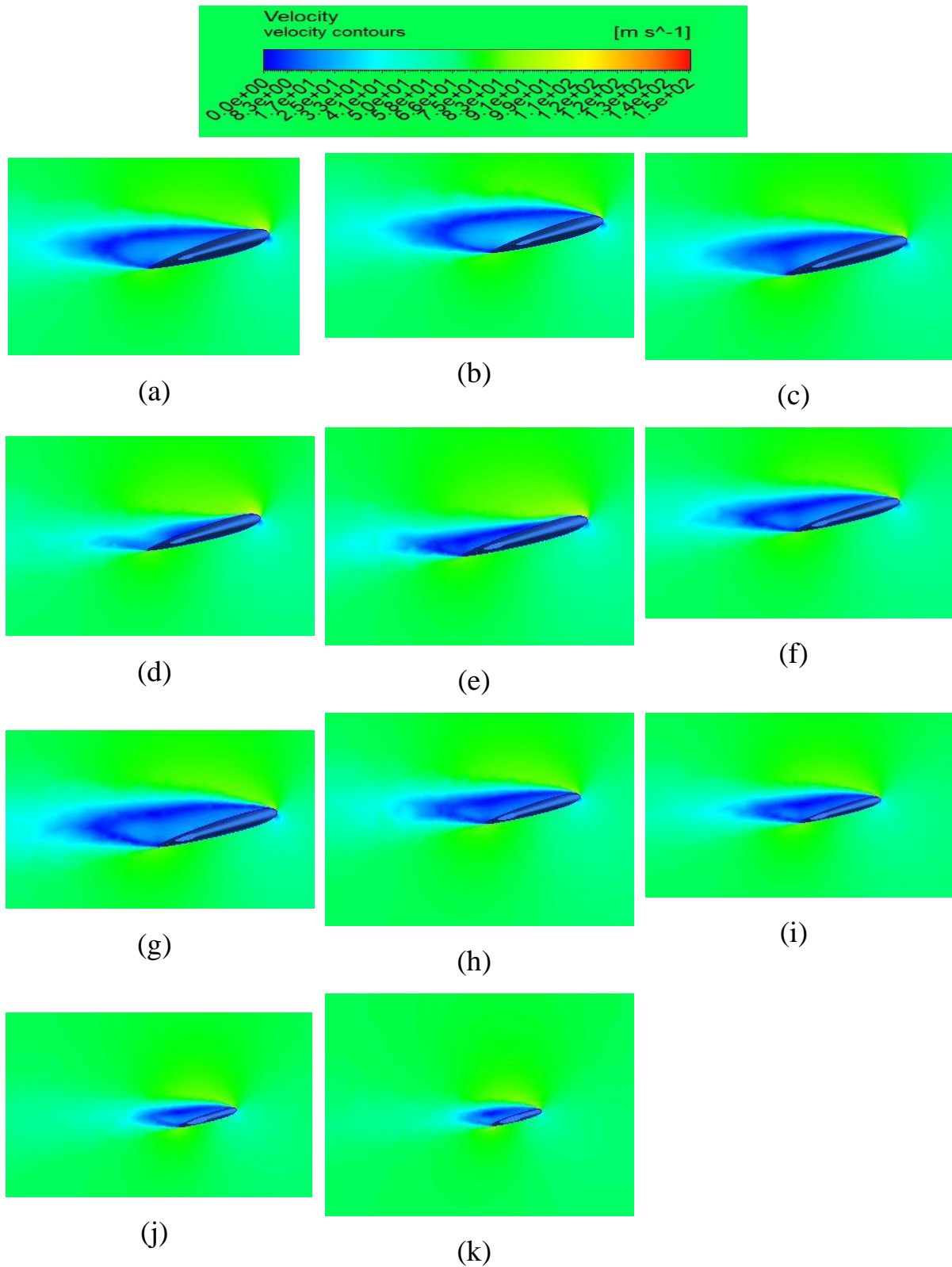
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1 Figure 6 Velocity contours around the A09λ57 wing peaks at cross-sections
2 located at a, b, c, d, and e at AoA 16°.



1 Figure 7 Velocity contours around the A09λ57 wing valleys at cross-sections
2 located at a, b, c, d, e, and f at AoA 16°.



1 Figure 8 Velocity contours around the baseline wing at (a) 27.6%, (b) 33%, (c)
2 38.7%, (d) 44%, (e) 53.8%, (f) 58.2%, (g) 62.7%, (h) 71.1%, (i) 75%, (j) 90.2%,
3 and (k) 93.8% of the span from the wing's hub.

1 The baseline wing has the worst aerodynamic behavior among the tested wings.
 2 The flow fields around the baseline and scalloped wings cause the high
 3 performance of the scalloped wings in comparison to the baseline wing. Figure 8
 4 shows the flow field around the baseline wing at the same positions as Figure 6,
 5 and Figure 7. Figure 8 shows that the flow is completely separated from the flow
 6 surface across the wing's chord, and at the different wing positions.
 7 The study's results showed that the wings with small amplitude and large
 8 wavelength tubercles have a $C_{L, \max}$ than the baseline wing at the baseline wing.
 9 Whereas Abate et al. [9], and Lohry et al. [11] results have an agreement with the
 10 study's optimum configuration, Hansen et al. [3], and Paula et al. [12] obtained a
 11 different optimum configuration of small amplitude and small wavelength.
 12 Further study is needed for the flow field structure and testing the performance of
 13 the optimum tubercles' configurations experimentally.

14 4. Conclusions

15 This study investigates the performance of wings with tubercles on the wing's
 16 leading edge and its dependence on the tubercle's amplitude and wavelength. The
 17 study found that the wing's performance greatly varies with the change of
 18 tubercle's amplitude and wavelength as

- 19 • Increasing amplitude increases the lift coefficient up to 23.61% and
 20 decreases the drag coefficient by 5.21% at mid-range amplitude. Any
 21 further increase in amplitude decreases lift and increases drag.
- 22 • Reducing wavelength also increases lift coefficient up to 21.55% and
 23 decreases drag coefficient by 9.50% in the case of mid-range wavelength.
 24 Any further reduction in wavelength decreases lift coefficient and increases
 25 drag coefficient.
- 26 • Flow visualization shows that the flow is completely separated from the
 27 upper surface of the baseline wing at the angle of attack 16° .

- 1 • Flow visualization shows the formulation of attached and separated zones
2 on the scalloped wings' surfaces. These zones cause the improvement in
3 the wing's performance in the post-stall flow regime and the performance
4 degradation in the pre-stall flow regime.

5 References

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